




Author Correction to: PSO Aided Adaptive Complementary Filter for Attitude Estimation

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The original article, unfortunately, contained an error.

The equation (5) in page number 4 of the article should be read as follows:

$$\psi_m = \tan^{-1} \left(\frac{m_z \sin \phi - m_y \cos \phi}{m_x \cos \theta + m_y \sin \theta \sin \phi + m_z \sin \theta \cos \phi} \right) \quad (5)$$

The online version of the original article can be found at
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