# Design and Implementation of Multilevel Inverters for Fuel Cell Energy Conversion System 

Dhanamjayulu C ${ }^{1,2}$, Member, IEEE, Shaik Reddi Khasim ${ }^{1}$, P. Sanjeevikumar ${ }^{2}$, Senior Member, IEEE, Arunkumar G ${ }^{1}$, Member, IEEE, Jens Bo Holm-Nielsen², Senior Member, IEEE, Frede Blaabjerg ${ }^{3}$, Fellow, IEEE,<br>${ }^{1}$ School of Electrical Engineering, Vellore Institute of Technology (VIT) University, Vellore, Tamilnadu, India.<br>${ }^{2}$ Center for Bioenergy and Green Engineering, Department of Energy Technology, Aalborg University, Esbjerg, Denmark<br>${ }^{3}$ Center of Reliable Power Electronics (CORPE), Department of Energy Technology, Aalborg University, Aalborg, Denmark.<br>Corresponding author: C. Dhanamjayulu (e-mail: dhanamjayulu.c@vit.ac.in) and P. Sanjeevikumar (e-mail: san@et.aau.dk)<br>"This project is carried out under the Project No. 19-MG06AAU, Danida Mobility Grant, responsible for the Ministry of Foreign Affairs of Denmark (MFA), Act 7 on Denmark's International Development Cooperation."


#### Abstract

Power converter plays a significant role in Proton Exchange Membrane Fuel Cell (PEMFC) energy generation systems, which is an alternative of distributed energy generation systems. So there creates a demand for high-quality power conditioning used in PEMFC systems. This paper proposes a converter topology as a power interface and also introduced a multilevel inverter topology for various levels of operation. The converter steps up the input voltage to the rated voltage and transforms to the DC bus, the multilevel inverter converts the voltage to AC and feeds to AC loads. In this paper, we develop an entire unit stack, which can produce an output with positive and zero sequences. The addition of H -bridge to the fundamental unit known to be an advance cascaded H -bridge multilevel inverter resulting in the formation of all sequences like positive, zero and negative levels. The conventional multilevel inverters are compared with the proposed inverters in terms of switch count, DC sources, diodes, through which the lesser requirement of components in a multilevel inverter is possible to observe, which results in the reduction in cost, dv/dt stress, component space of the driver circuit. With this implementation, the better possibility of control, increase the quality of output, reliability of the inverter with a reduced THD, and stress. The converter output is tested and verified in MATLAB, and the respective results of the different levels like five, seven and fifteen of a single-phase cascaded inverter are tested experimentally and in MATLAB Simulink.


INDEX TERMS Multilevel Inverter (MLI), Proton exchange membrane fuel cell (PEMFC), Converter, Total Harmonics Distortion (THD).

## I. INTRODUCTION

The basic configuration of inverters is of two-level, where the many drawbacks exist like input voltage is twice than that of the output voltage resulting in the severe harmonic distortions, high switching losses \& frequency. It restricts these to only low-power applications as the power handling capacity is less [1]. Hence, the evolution of multilevel inverters (MLI) came into existence to wipe out the described disadvantages and to provide better reliability and higher in quality of output waveform. The multilevel inverter is an ideal choice to choose for high and medium power applications with its harmonic reduction difference with a conventional inverter with the
same power in output and avoiding in increasing the switching frequency [2-4]. Multilevel inverters usually come in three forms [5], namely neutral clamping point (NPC), clamping diode (DCM) [6], flying capacitor (FLC) and cascaded H(CHB) [7-8]. The promising energy sources nowadays are the Renewable sources of energy such as solar panels and the fuel cell for the distributed generation systems [9-12]. From solar panel and fuel cell stacks, it uses the energy generation for energy transformation to feed the AC loads using power electronic devices with DC-AC, DC-DC conversion. It maintains the constant DC voltage at the DC bus by the stepup operation of the converter, and the inverter converts DC to

AC and transforms the DC bus voltage to the AC loads. The way of electricity generation is from a fuel cell, which is an electrochemical device. The mixture of air and fuel are the standard inputs for the fuel cell, converts to water and the electric nature to the chemical reaction [13-14]. Hydrogen plays a significant role in the fuel cell, which can operate parallel with internal combustion engines of the vehicles based on its availability. When the vehicles are on load, the battery characteristics are like a fuel cell. Sir William Robert Grove developed his first fuel cell in 1839.

Further, Sir Francis Bacon developed a usable fuel cell in 1950 with a capacity of 5 kW . Since then, these are popular and used for residential, industrial, and commercial purposes as primary power sources. In the current scenario, the attention towards fuel cells automobile industries for the development of eco-friendly vehicles. There are various types of multilevel inverters such as diode clamped (DC) [6], flying capacitor ( FC ), cascaded H-bridge ( CHB ), and a neutral point clamped (NPC). In both the flying capacitor multilevel inverters and neutral point clamped MLI, the balancing of capacitor voltage is the main problem because of which these are limited to only five-level not able to cascade, and output voltage reduces to half of the input voltage provides very high switching losses with high switching frequency. The diode clamping and capacitor voltage balancing are unnecessary for the cascaded multilevel inverters (conventional). Even in the CHB inverters, there is a clean possibility to get the higher output levels as these are series-connected: exempting the usage of DC sources is more. The proposed topology requires a smaller number of switches with which we can reduce the requirement of driver circuits compared with the conventional cascaded multilevel inverter [15]. There is a possibility of a reduction in the $\mathrm{dv} / \mathrm{dt}$ stress on each switch with the usage of more DC sources, and it becomes reliable, straightforward with less circuit space, and the cost gets reduced [16]. There are many
fundamental units and it imports various cascaded multilevel inverters [17-20].

In this paper, a fuel cell-based multilevel inverter is proposed. The basic units are in series to have a higher output level and reduced switch count. The addition of H-bridge achieves both positive and negative levels where the FC and DC are absent. The output constraints of the proposed multilevel inverter with five, seven, and fifteen levels are simulated in MATLAB, and it illustrates the results. The leftover part of this paper is organized as: The modeling of the proposed system is analyzed in section-2. The 4-level boost converter with PEMFC with ANFIS MPPT technique is presented in section-3. Section-4 explains the simulation and experimental results of developed MLI topologies. Power loss calculations of the developed MLI are done in section-5, parameters comparison among the proposed MLI with various topologies are presented in section-6, and finally, conclusions are given in section-7.

## II. PROTON EXCHANGE MEMBRANE FUEL CELL

The basic structure of the fuel cell is, as shown in Fig. 1 [21]. Electrochemical conversion is the principle involved in it. A fuel cell comprises two electrodes known as anode and cathode. When the anode is fed with hydrogen fuel, the catalyst activates with the separation of positive and negative ions. The generation of electricity happens with the mixture of hydrogen and oxygen in the cell in with the electrolyte. It produces only heat and water in this process, which is wastage, and the emission of gasses is absent [22]. It shows the principle involved in the fuel cell operation in Eq. (1).

It shows the operating principle of the fuel cell in Eq. (1).
$2 \mathrm{H}_{2}(\mathrm{~g})+\mathrm{O}_{2}(\mathrm{~g}) \rightarrow 2 \mathrm{H}_{2} \mathrm{O}+$ energy
It shows the chemical equation at cathode and anode in Equations. (2) and (3).
At cathode: $\mathrm{H}_{2} \rightarrow 2 \mathrm{H}^{+}+2 e^{-}$
At anode: $\frac{1}{2} \mathrm{O}_{2}+2 \mathrm{H}^{+}+2 e^{-} \rightarrow \mathrm{H}_{2} \mathrm{O}$


Because of the reaction of $\mathrm{O}_{2}$ and $\mathrm{H}_{2}, 1.23 \mathrm{~V}$ is developed theoretically. Ohmic and activation losses reduce the voltage to be less than 1.23 V [23]. In general, there are various types of fuel cells based on electrolyte materials like Alkaline Fuel Cell (AFC), Molten Carbonate Fuel Cell (MCFC), Phosphoric Acid Fuel Cell (PAFC), Proton Exchange Membrane Fuel Cell (PEMFC), and Solid Oxide Fuel Cell (SOFC) [24-25]. In these, PEMFC, DMFC, AFC, and PAFC having an operating temperature of less than 250 oC . MCFC and SOFC having a high operating temperature of more than 500 oC . The automobile field is the most starving of a fuel cell. In this scenario, the popular in automotive is PEMFC where the power density is high, nominal operating temperature, and very precise [26-27].
The mathematical modeling of PEMFC is:
The PEMFC output voltage is [28]
$V_{F C}=E_{\text {nerst }}-V_{\text {ohm }}-V_{\text {act }}-V_{\text {Con }}$
Where $E_{\text {nernst }}$ is the open-circuited thermodynamic voltage;
$\mathrm{V}_{\text {ohm }}$ is the ohmic voltage $\mathrm{V}_{\text {act, }}$, and $\mathrm{V}_{\text {con }}$ is the activation and concentrated voltages, respectively.
$E_{\text {nernst }}$ is determined: [29-30].
$E_{\text {Nerst }}=1.22-8.5 e^{-4}\left(T_{F C}-298.15\right)+$
$4.308 e^{-5}\left[\ln \left(P_{H_{2}}\right)+0.5 \ln \left(P_{O_{2}}\right)\right]$
Where $\mathrm{T}_{\mathrm{FC}}$ is PEMFC cell temperature, $\mathrm{P}_{\mathrm{H} 2}$ and $\mathrm{P}_{\mathrm{O} 2}$ are the partial pressures, respectively.

The expression of ohmic voltage is: [31-32].
$V_{\text {ohm }}=I_{\text {cell }}\left(R_{M}+R_{C}\right)$
Where $R_{C}$ is the resistance of a proton and $R_{M}$ is the equivalent of resistance. $\mathrm{R}_{\mathrm{M}}$ is given by.
$R_{M}=\frac{\rho_{m} L}{A}$
$\rho_{m}=\frac{181.6\left[1+0.03 J+0.062\left(\frac{T_{F C}}{303}\right)^{2} J^{2.5}\right]}{[G-0.634-3 J] e^{\frac{4.18\left(T_{F C}\right.}{F C}} \frac{F C}{F C}}$
Where $\rho_{m}$ is the membrane specific resistivity, L is thickness, A is the area, G is water content, and J is the current density of the membrane. J is defined as
$J=\frac{I_{\text {cell }}}{A}$
It represents the activation voltage in the parametric form of:
$V_{\text {act }}=\left(\zeta_{1} \zeta_{2} T_{F C}+\zeta_{3} T_{F C} \ln \left(C_{O_{2}}\right)+\zeta_{4} T_{F C} \ln \left(I_{\text {cell }}\right)\right)$
Where $\zeta_{1}, \zeta_{2}, \zeta_{3}$ and $\zeta_{4}$ are each cell coefficients, it expresses the oxygen concentration CO 2 as
$C_{O_{2}}=\frac{P_{O_{2}}}{\left(5.08 e^{6}\right) e^{\left(\frac{-498}{T_{F C}}\right)}}$
The concentration overvoltage is given by
$V_{C o n}=-\frac{R T_{F C}}{n F} \ln \left(1-\frac{J}{J_{\max }}\right)$
where $\mathrm{F}=$ Faraday's constant, $\mathrm{R}=$ gas constant, Jmax= Maximum current density.
III. PEMFC BASED DC-DC CONVERTER

The 4-level boost converter [33] has seven capacitors, one switch and seven diodes, as shown in Fig. 2.

$\mathrm{V}_{\mathrm{o}}$ is the output voltage of the converter which is the product of the number of levels N and the capacitor voltage Vc is given by

$$
\begin{equation*}
V_{o}=N \times V_{c}=\frac{N \times V_{i n}}{(1-D)} \tag{13}
\end{equation*}
$$

Where $\mathrm{V}_{\text {in }}$ is the input voltage, D is the duty cycle.
$D=\frac{T_{o n}}{T}$
Where $\mathrm{T}_{\text {on }}$ is on-state of the switch, T is the total time period. At the instant of the closure of switch S , the voltage at the capacitance $C_{6}$ is less than $C_{7}$, at this point $C_{7}$ clamps $C_{6}$ voltage using diode $\mathrm{D}_{6}$ along with the switch. Similarly, if the voltages at $\mathrm{C}_{4}$ and $\mathrm{C}_{6}$ are lesser than the capacitances $\mathrm{C}_{5}$, and $\mathrm{C}_{7}$, at this point $\mathrm{C}_{5}$, and $\mathrm{C}_{7}$ clamp the voltages at $\mathrm{C}_{4}$, and $\mathrm{C}_{6}$ using diode $\mathrm{D}_{4}$ along with the switch. Correspondingly, $\mathrm{C}_{3}, \mathrm{C}_{5}$, and C 7 clamp the voltages at $\mathrm{C}_{2}, \mathrm{C}_{4}$, and $\mathrm{C}_{6}$. At the instant when the switch is open, the inductor current follows the diode $\mathrm{D}_{7}$ and hence the capacitor $\mathrm{C}_{7}$ gets charged. All inputs, inductor voltage, and $\mathrm{C}_{6}$ clamp the voltages at $\mathrm{C}_{5}$ and $\mathrm{C}_{7}$ through the diode $\mathrm{D}_{5}$ when $\mathrm{D}_{7}$ conducts. Similarly, the inductor voltage and $\mathrm{V}_{\mathrm{IN}}, \mathrm{C}_{4}$, and $\mathrm{C}_{6}$ clamp the voltages at $\mathrm{C}_{3}$, $\mathrm{C}_{5}$, and $\mathrm{C}_{7}$ through the diode $\mathrm{D}_{3}$. At long last, inductor voltage and $\mathrm{V}_{\text {IN }}$ alongside $\mathrm{C}_{2}, \mathrm{C}_{4}$, and $\mathrm{C}_{6}$ clips the voltages crosswise at $C_{1}, C_{3}, C_{5}$, and $C_{7}$. It is seen that the diodes $D_{1}, D_{3}, D_{5}$, and $\mathrm{D}_{7}$ switches constantly. It is supplemented by the diodes $\mathrm{D}_{2}$,
$\mathrm{D}_{4}$, and D6 along with the switch. Table I. shows the experimental parameters

Table I
PARAMETERS OF THE PROPOSED SYSTEM

| $\mathrm{V}_{\mathrm{FC}}=\mathrm{V}_{\text {in }}$ | 48 V |
| :--- | :--- |
| $\mathrm{~V}_{\mathrm{o}}$ | 400 V |
| Switching frequency, $\mathrm{f}_{\mathrm{sw}}$ | 100 kHz |
| Inductor L, with $\mathrm{R}_{\mathrm{L}}$ | $500 \mu \mathrm{H}$ with $\mathrm{R}_{\mathrm{L}}=0.35 \Omega$ |
| Capacitor, C | $10 \mu \mathrm{~F}$ |
| Duty cycle, D | $52.37 \%$ |
| dSPACE controller | RTI1104 |
| Fuel cell | MT91S130-1000 |
| IGBT | IGBT CM75DU-12, 600V, 75 A |
| Resistive Load (Lamp) | $100 \Omega$ |
| Inductive Load | 175 mH |
| Motor Load | Single-phase, 230V, 0.5 HP |

## A. ANFIS MPPT Controller

A combination of neural networks and fuzzy systems produces an ANFIS system [34]. This system can learn neural networks, which is a significant advantage. There are five layers with dual inputs ( x and y ) and single-output ( F ). The if-then rules of the fuzzy system are given below:
Rule 1: if $x$ is $A_{1}$ and $y$ is $B_{1}$, then $F_{1}=p_{1} X+q_{1} Y+r_{1}$
Rule 2: if $x$ is $A_{2}$ and $y$ is $B_{2}$, then $F_{1}=p_{2} X+q_{2} Y+r_{2}$
It can vary the system temperature from 300 K to 340 K in a step of 20K by training ANFIS. By using these data sets, it generates a fuzzy interference system, where the parameters


FIGURE 3. The 4-level converter \& FC Simulation waveforms


FIGURE 4. The 4-level converter \& FC Simulation waveforms
are tuned with a hybrid optimization method with the combination of least square and backpropagation algorithms. The proposed converter is simulated in MATLAB and validated experimentally with the dSPACE RTI1104 controller. The fuel cell stock input voltage $\mathrm{V}_{\text {In }} \mathrm{FC}=48 \mathrm{~V}$, switching frequency 100 kHz , inductor 500 H , resistance 0.35 -ohm, capacitor 10 F with duty cycle $53.37 \%$ for obtaining $\mathrm{V}_{\text {odc }}=400 \mathrm{~V}$ are shown in Fig. 3 and Fig. 4 respectively. The rules and decisions follow: For the estimation of accuracy of the ANFIS MPPT controller.
several simulations and experimentally are done in MATLAB/Simulink and dSPACE RTI1104 controller for the nominal operations of FC and the transient variations in the temperature of cells. It shows the DC link voltage of the FC along with the ANFIS MPPT controller in Fig. 1. The FC considered is having the output voltage is 48 V and is boosted to 400 V maintained at DC link using ANFIS [34].

## IV. DEVELOPED STRUCTURE WITH PMFC

The proposed PEMFC inverter composed of a DC-DC converter supplied with fuel cell and it feeds the regulated DC output voltage from the converter to DC bus where the rated voltage can be maintained. It shows the fundamental unit in Fig. 5 comprises five switches from $S_{1}$ to $S_{5}$ and three DC sources $\mathrm{V}_{1}, \mathrm{~V}_{2}$ and $\mathrm{V}_{3}$ derived from DC bus voltage.


The switches (S2, S4), (S1, S2, S3, S5) and (S1, S3, S4, S5) are to take care that these should not turn on at an instant of time, to avoid short circuit. The various positive voltage levels only can be got. The basic units are to be connected in series to increase the voltage levels, along with this arrangement, the voltage of $\mathrm{V}_{\mathrm{A}}$ is connected in series with a switch SA, and parallel to switch SB shown in Fig. 5.1, where the lowest amplitude of voltage level can be possible. A short circuit may occur with the simultaneous operation of the switches SA and SB, which is avoided.
The output voltage $\mathrm{V}_{0}(\mathrm{t})$ is
$V_{0}(t)=V_{0,1}(t)+V_{0,2}(t)+V_{0,3}(t)+-----+$
$V_{0, n}(t)+V_{A}(t)$

Multidisciplinary : Rapid Review ; Open Access Journal


FIGURE 5.1. Developed Cascaded Multilevel Inverter.

There are only positive levels in the output voltage of a basic unit. To get the negative levels, an H-Bridge is added to the developed arrangement shown in Fig. 5.1. H-Bridge contains the switches $\mathrm{S}_{\mathrm{H} 1}$ to $\mathrm{S}_{\mathrm{H} 4}$, where the operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ produces the positive levels and the operation of $\mathrm{S}_{\mathrm{H} 2}$ and $S_{H 3}$ produces the negative levels of output voltage, resembles to be a multilevel inverter.

It cascades the developed fundamental units to get several levels of output like 5-level, 7-level. 15 levels shown below. The 5-level output can be got with the fundamental unit only, the several modes of operation, expected output waveform with the switching pulses could be represented below. Even though the switch count is high in the 5 -level MLI, this is tested experimentally with a prototype, and we design further 7 and 15 level MLI with less device count and low THD.

## A. PROPOSED 5-LEVEL MLI

The proposed 5-level MLI is designed with a developed fundamental unit without the addition of the circuit components. The circuit contains fewer number of switches
compared with the existing topologies. This topology comprises nine switches with three DC sources without capacitors, diodes shown in Fig. 6. The power quality issues like THD, a smaller number of switches, dv/dt stress are minimized with this developed multilevel inverter. The circuit comprises three DC sources $\mathrm{V}_{1}, \mathrm{~V}_{2}, \mathrm{~V}_{3}$, and nine switches $S_{1}, S_{2} S_{3}, S_{4}, S_{5}, S_{H 1}, S_{H 2}, S_{H 3}$ and $S_{H 4}$ are the modules of H-Bridge. The arrangement reduces the additional DC source requirement and also simplifies the number of switches needed. The operating modes of the 5Level MLI are shown in Fig. 7.
In this section, it illustrates the developed MLI operation with the steady-state voltage levels in several modes of operation. Here, all the DC source voltages are having equal magnitude, i.e., $\mathrm{V}_{1}=\mathrm{V}_{2}=\mathrm{V}_{3}=\mathrm{V}_{\mathrm{dc}}=133.33 \mathrm{~V}$. Mode-1: In this mode of operation, the switches $S_{1}, S_{2}, S_{3}, S_{H 1}, S_{H 4}$ are in conduction state, hence the load current $\mathrm{I}_{0}$ path is through $\mathrm{V}_{1^{-}}$ $\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{D}_{3}-\mathrm{V}_{3}-\mathrm{D}_{2}-\mathrm{V}_{2}-\mathrm{D}_{1}$. As all the DC sources are of the same magnitude, the addition of $\mathrm{V}_{1}, \mathrm{~V}_{2}, \mathrm{~V}_{3}$ voltages can produce $3 \mathrm{~V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ in an H -


FIGURE 6. The basic structure of 5-level MLI
Bridge produces a positive level of voltage. The output voltage level is $+3 \mathrm{~V}_{\mathrm{dc}}$ i.e., +400 volts.
Mode-2: In this mode, the switches $S_{1}, S_{3}, S_{4}, S_{H 1}, S_{H 4}$ are in conduction state; hence the load current $I_{0}$ path is through
$\mathrm{V}_{1}-\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{D}_{3}-\mathrm{V}_{3}-\mathrm{D}_{4}-\mathrm{D}_{1}$. The voltages $\mathrm{V}_{1}, \mathrm{~V}_{3}$ act in the circuits resulting in the formation of 2 Vdc . The operation of switches $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ in an H -Bridge produces a positive level of voltage. The output voltage is $2 \mathrm{~V}_{\mathrm{dc}}$, i.e., +266.66 volts. Mode-3: In this mode, the switches $\mathrm{S}_{5}, \mathrm{~S}_{\mathrm{H} 1}, \mathrm{~S}_{\mathrm{H} 4}$ are in conduction state; hence the path follows: $\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{S}_{\mathrm{H} 5}$. No DC voltage source acts in the circuit produce $0 \mathrm{~V}_{\mathrm{dc}}$ output voltage. Mode-4: In this mode, the switches $S_{5}, S_{H 3}, S_{H 2}$ are in conduction state; hence the path follows: $\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{D}_{5}$. As no DC voltage source acts in the circuit, produce $0 \mathrm{~V}_{\mathrm{dc}}$ output voltage. Mode-5: In this mode, the switches $S_{1}, S_{4}, S_{3}, S_{H 2}$, $\mathrm{S}_{\mathrm{H} 3}$ are in conduction state; hence the load current $\mathrm{I}_{0}$ path is through $\mathrm{V}_{1}-\mathrm{S}_{\mathrm{H} 3}-\mathrm{S}_{\mathrm{H} 2}-\mathrm{D}_{3}-\mathrm{V}_{3}-\mathrm{D}_{4}-\mathrm{D}_{1}$. The voltages $\mathrm{V}_{1}, \mathrm{~V}_{3}$ act in the circuits resulting in the formation of 2 Vdc . The operation of switches $\mathrm{S}_{\mathrm{H} 3}$ and $\mathrm{S}_{\mathrm{H} 2}$ in an H -Bridge produces a negative level of voltage. The output voltage level is $2 \mathrm{~V}_{\mathrm{dc}}$, i.e., -266.66 volts. Mode-6: In this mode, the switches $\mathrm{S}_{1}, \mathrm{~S}_{\mathrm{H} 3}, \mathrm{~S}_{\mathrm{H} 2}$ are in conduction state; hence the load of current $\mathrm{I}_{0}$ passes through $\mathrm{V}_{1}-\mathrm{S}_{\mathrm{H} 3}-\mathrm{S}_{\mathrm{H} 2}-\mathrm{D}_{3}-\mathrm{V}_{3}-\mathrm{D}_{2}-\mathrm{V}_{2}-\mathrm{D}_{1}$. As the voltage sources $\mathrm{V}_{1}, \mathrm{~V}_{2}$, $V_{3}$.


FIGURE 7. Modes of operation of the developed 5-Level MLI topology
(a): Mode-1, (b) Mode-2, (c) Mode-3, (d) Mode-4, (e) Mode-5, (f) Mode-6, (g) 5-Level expected output voltage waveform

Table II

## Mode

 Switch State|  | Output Voltage ( $\mathrm{V}_{\mathrm{o}}$ ) Volts | $\mathrm{S}_{1}$ | $\mathrm{S}_{2}$ | S3 | $\mathrm{S}_{4}$ | $\mathrm{S}_{5}$ | $\mathbf{S}_{\mathrm{H} 1}$ | $\mathrm{S}_{\mathrm{H} 2}$ | $\mathrm{S}_{\mathrm{H} 3}$ | $\mathbf{S H}_{\mathbf{H}}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $2 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 |
| 2 | $\mathrm{V}_{\mathrm{dc}}$ | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 |
| 3 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 |
|  |  | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 |
| 4 | $-\mathrm{V}_{\text {dc }}$ | 1 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 |
| 5 | $-2 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1 | 0 |



FIGURE 8(a). Simulation output voltage and current waveforms of a fivelevel inverter


FIGURE 8(b). Experimental output voltage and current waveforms of a five-level inverter

## B. PROPOSED 7-LEVEL MLI


acts in the circuit produced an output voltage of $3 \mathrm{~V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 3}$ and $\mathrm{S}_{\mathrm{H} 2}$ in an H -Bridge produces a negative level of voltage. The output voltage level is $-3 \mathrm{~V}_{\mathrm{dc}}$, i.e., -400 V . It shows the standard output voltage waveform in Fig. 7(g). The respective switching table for the developed 7-level MLI is illustrated in Table II. It shows the simulation and experimental obtained results in Fig. 8(a) \& (b). The hardware specifications used in the design of five levels of MLI are shown in Table I

The proposed 7-level MLI is designed with a developed fundamental unit with the addition of one extra switch $S_{6}$ connected parallel to the series combination of the switch $S_{1}$ and voltage $\mathrm{V}_{1}$. The circuit contains a fewer number of switches compared with the existing topologies. This topology has ten switches with three DC sources without capacitors, diodes shown in Fig. 9. The power quality issues like THD, a smaller number of switches, dv/dt stress are minimized with this developed multilevel inverter.

In this module, the developed MLI operation is illustrated in detail in Fig. 10 with the steady-state voltage levels in several modes of operation. Here, all the DC source voltages are having equal magnitude, i.e., $\mathrm{V}_{1}=\mathrm{V}_{2}=\mathrm{V}_{3}=\mathrm{V}_{\mathrm{dc}}=133.33 \mathrm{~V}$. Mode-1: In this mode, the switches, $S_{1}, S_{2}, S_{3}, S_{H 1}, S_{H 4}$ are in conduction state; hence the load current $\mathrm{I}_{0}$ path is through $\mathrm{V}_{1^{-}}$ $\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{D}_{3}-\mathrm{V}_{3}-\mathrm{D}_{2}-\mathrm{V}_{2}-\mathrm{D}_{1}$. As all the dc sources are of the same magnitude, the addition of $\mathrm{V}_{1}, \mathrm{~V}_{2}, \mathrm{~V}_{3}$ voltages can produce $3 \mathrm{~V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ in an $\mathrm{H}-$ Bridge produces a positive level of voltage. The output voltage level is $+3 \mathrm{~V}_{\mathrm{dc}}$, i.e., +400 volts. Mode- 2 : In this mode, the switches $\mathrm{S}_{2}, \mathrm{~S}_{3}, \mathrm{~S}_{6}, \mathrm{~S}_{\mathrm{H} 1}, \mathrm{~S}_{\mathrm{H} 4}$ are in conduction state; hence the load current $\mathrm{I}_{\mathrm{o}}$ path is through $\mathrm{V}_{3}-\mathrm{D}_{2}-\mathrm{V} 2-\mathrm{S}_{6}-\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}$. The voltages $\mathrm{V}_{2}, \mathrm{~V}_{3}$ act in the circuits resulting in the formation of $2 \mathrm{~V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ in an H -Bridge produces a positive level of voltage. The output voltage level is $+2 \mathrm{~V}_{\mathrm{dc}}$, i.e., +266.66 volts. Mode-3: In this mode, the switches $S_{3}, S_{4}, S_{6}, S_{H 1}, S_{H 4}$ are in conduction state; hence the load current $\mathrm{I}_{0}$ path is through $\mathrm{V}_{3}-\mathrm{S}_{4}-\mathrm{S}_{6}-\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{D}_{3}$. The voltages $\mathrm{V}_{3}$ acts in the circuit resulting in the formation of $\mathrm{V}_{\mathrm{O}}=\mathrm{V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ in an $\mathrm{H}-$ Bridge produces a positive level of voltage. The output voltage level is $+1 \mathrm{~V}_{\mathrm{dc}}$, i.e., $\mathrm{V}_{\mathrm{o}}=+133.33$ volts. Mode-4: In this mode, the switches $S_{5}, S_{H 1}, S_{H 4}$ are in conduction state; hence the path follows $\mathrm{S}_{\mathrm{H} 1}-\mathrm{S}_{\mathrm{H} 4}-\mathrm{S}_{5}$. No dc voltage source acts in the circuit produces $0 \mathrm{~V}_{\mathrm{dc}}$ output voltage. Hence $\mathrm{V}_{\mathrm{o}}=0$ volts. Mode-5: In this mode, the switches $S_{5}, S_{\mathrm{H} 3}, S_{\mathrm{H} 2}$ are in conduction state; hence the path follows $\mathrm{S}_{\mathrm{H} 3}-\mathrm{S}_{\mathrm{H} 2}-\mathrm{S}_{5}$. As no dc voltage source acts in the circuit, produces $0 \mathrm{~V}_{\mathrm{dc}}$ output


FIGURE 10. Modes of operation of the developed 7-Level MLI topology
(a): Mode-1, (b): Mode-2, (c): Mode-3, (d): Mode-4, (e): Mode-5, (f): Mode-6, (g): Mode-7, (h): Mode-8, (i): 7-Level expected output voltage waveform

Table III
SWITCHING STATES FOR THE DEVELOPED 7-LEVEL MLI

| Mode | Output Voltage ( $\mathbf{V}_{\mathrm{o}}$ ) Volts | Switch State |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathbf{S}_{1}$ | $\mathbf{S}_{2}$ | $\mathbf{S}_{3}$ | $\mathbf{S}_{4}$ | $\mathbf{S}_{5}$ | $\mathrm{S}_{6}$ | $\mathrm{S}_{\mathrm{H} 1}$ | $\mathrm{S}_{\mathrm{H} 2}$ | $\mathrm{S}_{\mathrm{H} 3}$ | $\mathrm{S}_{\mathrm{H} 4}$ |
| 1 | $3 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 2 | $2 \mathrm{~V}_{\text {dc }}$ | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 |
| 3 | $\mathrm{V}_{\mathrm{dc}}$ | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 1 |
| 4 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 4 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 5 | $-\mathrm{V}_{\mathrm{dc}}$ | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
| 6 | $-2 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 |
| 7 | $-3 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |



FIGURE 11(a). Simulation output voltage and current waveform of Seven-level inverter


FIGURE 11(b). Experimental output voltage and current waveforms of a
voltage. Hence $\mathrm{V}_{0}=0$ volts. Mode-6: In this mode, the switches $\mathrm{S}_{3}, \mathrm{~S}_{4}, \mathrm{~S}_{6}, \mathrm{~S}_{\mathrm{H} 3}, \mathrm{~S}_{\mathrm{H} 2}$ are in conduction state; hence the load current $\mathrm{I}_{\mathrm{o}}$ path is through $\mathrm{V}_{3}-\mathrm{S}_{4}-\mathrm{S}_{6}-\mathrm{S}_{\mathrm{H} 3}-\mathrm{S}_{\mathrm{H} 2}-\mathrm{D}_{3}$. The voltages $V_{3}$ acts in the circuit resulting in the formation of 1 Vdc . The operation of switches $\mathrm{S}_{\mathrm{H} 3}$ and $\mathrm{S}_{\mathrm{H} 2}$ in an H -Bridge produces a negative level of voltage. The output voltage level is $1 \mathrm{~V}_{\text {dc, }}$ i.e., $\mathrm{V}_{\mathrm{o}}=-133.33$ volts. Mode-7: In this mode, the switches $\mathrm{S}_{2}, \mathrm{~S}_{6}, \mathrm{~S}_{\mathrm{H} 3}, \mathrm{~S}_{\mathrm{H} 2}, \mathrm{~S}_{3}$ are in conduction state; hence the load of current $\mathrm{I}_{0}$ passes through $\mathrm{V}_{3}-\mathrm{D}_{2}-\mathrm{V}_{2}-\mathrm{S}_{6}-\mathrm{S}_{\mathrm{H} 3}-\mathrm{S}_{\mathrm{H} 2}-\mathrm{D}_{3}$. As two voltage sources $\mathrm{V}_{2}, \mathrm{~V}_{3}$ acts in the circuit produce an output voltage of $2 \mathrm{~V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 3}$ and $\mathrm{S}_{\mathrm{H} 2}$ in an H-Bridge produces a negative level of voltage. The output voltage level is $-2 \mathrm{~V}_{\mathrm{dc}}$, i.e., $\mathrm{V}_{\mathrm{o}}=-266.66 \mathrm{~V}$. Mode-8: In this mode, the switches $\mathrm{S}_{1}, \mathrm{~S}_{\mathrm{H} 3}, \mathrm{~S}_{\mathrm{H} 2}, \mathrm{~S}_{3}, \mathrm{~S}_{2}, \mathrm{~S}_{1}$ are in conduction state; hence the load of current $\mathrm{I}_{o}$ passes through $\mathrm{V}_{1}-\mathrm{S}_{\mathrm{H} 3}-\mathrm{S}_{\mathrm{H} 2}-\mathrm{D}_{3}-\mathrm{V}_{3}-\mathrm{D}_{2}-\mathrm{V}_{2}-\mathrm{D}_{1}$. As two voltage sources $\mathrm{V}_{1}$, $\mathrm{V}_{2}, \mathrm{~V}_{3}$ acts in the circuit produce an output voltage of $3 \mathrm{~V}_{\mathrm{dc}}$. The operation of switches $\mathrm{S}_{\mathrm{H} 3}$ and $\mathrm{S}_{\mathrm{H} 2}$ in an H-Bridge produces a negative level of voltage. The output voltage level is $-2 \mathrm{~V}_{\mathrm{dc}}$, i.e., $\mathrm{V}_{\mathrm{o}}=-400 \mathrm{~V}$. It shows the typical output voltage waveform in Fig. 10(i). The developed MLI operation can be viewed from the switching pulses generated according to the operation of switches. It can power the state of switches with ' 1 ' or ' 0 '. If the state of the switch is in ' 1 ', we turn it on. If
the state is in ' 0 ', it resembles it turns the switch off. The respective switching table for the developed 7 -level MLI is illustrated in Table III. We design the MLI with three equal magnitudes of voltages: $\mathrm{V}_{1}, \mathrm{~V}_{2}, \mathrm{~V}_{3}$ having 133.33 V each, therefore the $400 \mathrm{~V}, 4 \mathrm{~A}$ output voltage, and current with a load resistor of $100 \Omega$. It shows the simulation and experimental obtained results in Fig. 11(a) \& (b). With this arrangement, it is easy to get seven levels of output with which the power quality increases with a reduced THD. Table shows the hardware specifications used in the design of seven-level MLI I

## C. PROPOSED 15-LEVEL MLI

The proposed 15 -level MLI is designed with two developed fundamental units in cascade without the addition of circuit components. This topology consists of sixteen switches with seven DC sources without capacitors, diodes shown in Fig. 12. The power quality issues like THD, less number of switches, dv/dt stress are minimized with this developed multilevel inverter. The switches $\mathrm{S}_{\mathrm{H} 1}, \mathrm{~S}_{\mathrm{H} 2}, \mathrm{~S}_{\mathrm{H} 3}$, and SH 4 are connected in an H-Bridge, where the negative voltage levels can be produced. The 15 levels developed circuit is shown in Fig. 12. The operation of switches is shown in Table III and a few modes of operation of the developed 15 levels MLI is represented in Fig. 13, the expected output voltage waveform is shown in Fig. 13.


The developed MLI operation can be simply viewed from the switching pulses generated according to the operation of

(a): Mode-1, (b): Mode-2, (c): Mode-3, (d): Mode-13, (e): Mode-14, (f): 15-Level expected output voltage waveform
switches. It can power the state of switches with ' 1 ' or ' 0 '. If the state of the switch is in ' 1 ', we turn it on. If the state is in ' 0 ', it resembles it turns the switch off. The respective switching table for the developed 15 -level MLI is illustrated in Table IV. We design the MLI with three equal magnitudes of voltages: $\mathrm{V}_{1}, \mathrm{~V}_{2}, \mathrm{~V}_{3}$ having 58 V each, therefore the 400 V , 4 A output parameters with a load resistor of $100 \Omega$.
We simulate the developed cascaded MLI in MATLAB. The developed two units cascaded fifteen-level multilevel inverter simulation is shown in Fig. 13. It makes all the DC sources to be constant of 58 V , concerning this voltage, the waveforms of the voltage and current are got and shown in Fig. 16. Initially, the switches $S_{51}$ of unit-1, $S_{52}$ of unit-2, and $S_{B}$ are turned on. As it connects no DC voltage source in the circuit, the voltage becomes 0 V . The switch $\mathrm{S}_{51}$ of unit-1, $\mathrm{S}_{52}$ of unit-2, and $S_{A}$ are turned on, where the voltage source $V_{A}$ acts alone in the circuit forms an output voltage of +57 V with the H -Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ gives positive voltage level. Then, the switches $S_{51}$ of unit-1, $S_{12}, S_{32}, S_{42}$ of unit-2, and $S_{B}$ are turned on, where the voltage sources $V_{12}$ and $V_{32}$ acts alone in the circuit, getting the output voltage of +114 V with the H -Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ producing positive voltage levels. Then, the switches $S_{51}$ of unit-1, $S_{12}$, $S_{22}, S_{32}$, of unit-2, and $S_{B}$ are turned on, where the voltage sources $\mathrm{V}_{12}, \mathrm{~V}_{22}$, and $\mathrm{V}_{32}$ acts in the circuit getting the maximum output voltage of +171 V with the H -Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ producing positive voltage levels. Then, the switches $S_{51}$ of unit- $1, S_{12}, S_{22}, S_{32}$, of unit-2, and $S_{A}$ are turned on, where the voltage sources $V_{12}, V_{22}, V_{32}$, and $\mathrm{V}_{\mathrm{A}}$ acts in the circuit, getting the maximum output voltage of +228 V with the H -Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ producing positive voltage levels. Then, the switches $S_{11,} S_{31}, S_{41}$ of unit$1, S_{12}, S_{32}, S_{42}$ of unit-2, and $S_{A}$ are turned on, where the voltage sources $\mathrm{V}_{11}, \mathrm{~V}_{31}, \mathrm{~V}_{12}, \mathrm{~V}_{32}$, and $\mathrm{V}_{\mathrm{A}}$ acts in the circuit,
getting the output voltage of +285 V with the H -Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ producing positive voltage levels. Then, the switches $S_{11}, S_{31}, S_{41}$ of unit-1, $S_{12}, S_{22,} S_{32}$ of unit-2, and $S_{A}$ are turned on, where the voltage sources $V_{11}, V_{31}, V_{12}$, $\mathrm{V}_{22}, \mathrm{~V}_{32}$, and $\mathrm{V}_{\mathrm{A}}$ acts in the circuit, getting the output voltage of +342 V with the H -Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ producing positive voltage levels. Then, the switches $S_{11}, S_{21}$, $S_{31}$ of unit-1, $S_{12}, S_{22}, S_{32}$ of unit-2, and $S_{A}$ are turned on, where the voltage sources $\mathrm{V}_{11}, \mathrm{~V}_{21}, \mathrm{~V}_{31}, \mathrm{~V}_{12}, \mathrm{~V}_{22}, \mathrm{~V}_{32}$, and $\mathrm{V}_{\mathrm{A}}$ acts in the circuit, getting the output voltage of +400 V with the H Bridge operation of $\mathrm{S}_{\mathrm{H} 1}$ and $\mathrm{S}_{\mathrm{H} 4}$ producing positive voltage levels. We get hence the positive cycle of output voltage waveform. For obtaining, the negative cycle, the H-Bridge is operated with the switches $\mathrm{S}_{\mathrm{H} 2}$ and $\mathrm{S}_{\mathrm{H} 3}$ in all modes of operation of the multilevel inverter. Hence the fifteen levels that can be achieved at the output of MLI with simulation THD are shown in Fig. 14 and Fig. 15 respectively. The simulation and experimental output waveforms and THD can be got shown in Fig. 16, Fig. 17, Fig. 18, and Fig. 19, respectively. With this arrangement, we can get the fifteen levels of output with a smaller number of switches with which the power quality increases with a reduced THD. The developed cascaded fifteen levels multilevel inverter is implemented experimentally and the results with R-Load shown in Fig. 19, with L-Load shown in Fig. 20, with R in parallel with L load shown in Fig. 20, Fig. 21 shows the output waveforms with L in parallel with R load. The load is with a resistance of $100 \Omega$ are verified with a simulation output waveform, and the respective THD from simulation and experimental are got shown in Fig. 22 and Fig. 23. It shows the experimental setup in Fig. 24. It shows the hardware specifications used in the design of fifteen levels of MLI Table I.

TABLE IV
SWITCHING STATES FOR THE DEVELOPED 15-LEVEL MLI

| Mode | Output Voltage ( $\mathrm{V}_{\mathrm{o}}$ ) Volts | Switch State |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathrm{S}_{11}$ | $\mathbf{S}_{21}$ | $\mathbf{S}_{31}$ | $\mathbf{S}_{41}$ | $\mathrm{S}_{51}$ | $\mathrm{S}_{12}$ | $\mathbf{S}_{22}$ | $\mathrm{S}_{32}$ | $\mathrm{S}_{42}$ | $\mathbf{S}_{52}$ | $\mathbf{S}_{\text {A }}$ | $\mathbf{S}_{\text {B }}$ | $\mathrm{S}_{\mathrm{H} 1}$ | $\mathbf{S}_{\mathrm{H} 2}$ | $\mathrm{S}_{\mathrm{H} 3}$ | $\mathrm{S}_{\mathrm{H} 4}$ |
| 1 | $7 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 2 | $6 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 3 | $5 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 4 | $4 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 5 | $3 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 6 | $2 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 |
| 7 | $\mathrm{V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 |
| 8 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 0 | 1 |
| 8 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 9 | - $\mathrm{V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 0 |
| 10 | $-2 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 |
| 11 | $-3 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 12 | $-4 \mathrm{~V}_{\mathrm{dc}}$ | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 13 | $-5 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 14 | $-6 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 15 | $-7 \mathrm{~V}_{\mathrm{dc}}$ | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |



FIGURE 14. Simulation output voltage and current waveforms of a fifteen-level inverter


FIGURE 15. Simulation THD


FIGURE 16. Experimental output waveform (Vo)


FIGURE 17. Experimental output waveform with R Load


FIGURE 18. Experimental output waveform with L Load


FIGURE 19. Experimental output waveform with R||L Load


FIGURE 20. Experimental output waveform with L||R Load


FIGURE 21. Experimental THD


FIGURE 22. Experimental setup

## V. POWER LOSS CALCULATION

The crucial power loss of switches in MLIs are from conduction and switching losses [13] the switching losses and conduction losses dominate high switching frequencies are more effective in low switching frequency. Conduction loss of IGBT with antiparallel diode is because of the onstate condition of resistance and voltages of both transistors and diode. When $\mathrm{V}_{\mathrm{S}}$ is applied to switches, $\mathrm{R}_{\mathrm{S}}, \mathrm{R}_{\mathrm{d}}$ is the internal resistances of the transistor, diode respectively and $\mathrm{V}_{\mathrm{d}}$ is the on-state voltage. The conduction losses $\left(\mathrm{P}_{\mathrm{c}}\right)$ of diode $\mathrm{P}_{\mathrm{cd}}$ and transistor $\mathrm{P}_{\mathrm{cs}}$ are determined as follows [39-40] $\boldsymbol{P}_{\boldsymbol{c} \boldsymbol{d}}(\mathrm{t})=\mathrm{V}_{\mathrm{d}} \mathrm{i}(\mathrm{t})+\mathrm{R}_{\mathrm{d}} \mathrm{i} 2(\mathrm{t})$
$\boldsymbol{P}_{\boldsymbol{c s}}(\mathrm{t})=\mathrm{V}_{\mathrm{s}} \mathrm{i}(\mathrm{t})+\left[\mathrm{R}_{\mathrm{s}} \mathrm{i} \beta(\mathrm{t})\right] \mathrm{i}(\mathrm{t})$
Where $\beta$ is a constant calculated from characteristics of a power switch.
Assuming, there are $\mathrm{N}_{\mathrm{s}, \text { on }}$ switches and $\mathrm{N}_{\mathrm{d}, \text { on }}$ diodes are conduction at the time of instant ' $t$ ' then the multilevel average conduction power losses are [39-40]
$P_{C U}=\frac{1}{\pi} \int_{0}^{\pi}\left[N_{s, o n}(t) P_{c s}(t)+N_{d, o n}(t) P_{c d}(t)\right] d t$
$\boldsymbol{P}_{\boldsymbol{C U}}=\frac{1}{\pi} \int_{\mathbf{0}}^{\pi}\left[\boldsymbol{N}_{\boldsymbol{s}, \boldsymbol{o n}}(\boldsymbol{t})\left\{\boldsymbol{V}_{\boldsymbol{s}} \boldsymbol{i}(\mathrm{t})+\boldsymbol{R}_{\boldsymbol{s}} \boldsymbol{i}^{\boldsymbol{\beta}}(\mathrm{t})\right\}+\right.$
$N_{d, o n}(t)\left\{V_{d} i(t)+R_{d} i(t)\right] i(t) d t$
In the proposed MLI topology there is a bi-directional switch $S_{a}$, and it conducts at the time of instant ${ }^{\prime} t$ ' then the average conduction losses are [39-40]

$$
\begin{equation*}
P_{C B}=\frac{1}{\pi} \int_{0}^{\pi}\left[V_{s}(t)+V_{d}(t)+R_{s} i^{\beta}(t)+R_{d} i(t)\right] i(t) d(t) \tag{21}
\end{equation*}
$$

Consider the output current is sinusoidal, then

## VI. COMPARISON STUDIES

The symmetrical configuration of the presented MLI is compared with various levels like 5 level, 7 levels, 15 levels symmetrical configuration of the multilevel inverters such as Cascaded H-bridge (CHB), Flying capacitors (FC), Neutral point clamped (NPC) and the several topologies presented. The components with their output voltage levels for correspondent topologies considered is calculated from the equations in Table IV and tabulated in the respective levels of operation tables. And the components count per level factor $\mathrm{F}_{\mathrm{ccl}}$ is calculated from equation 31.

$$
\begin{equation*}
\mathrm{F}_{\mathrm{ccl}}=\frac{\mathrm{N}_{\mathrm{s}}+\mathrm{N}_{\mathrm{d}}+\mathrm{N}_{\mathrm{cap}}+\mathrm{N}_{\mathrm{dk}}+\mathrm{n}}{\mathrm{~N}_{\mathrm{Lev}}} \tag{31}
\end{equation*}
$$

$i(t)=i_{m} \sin (t)$
The simplified average conduction losses of a bi-directional switch can be calculated from equation (20) and (21)
$P_{C B}=\frac{2}{\pi} \mathrm{i}_{\mathrm{m}}\left[\mathrm{V}_{\mathrm{s}}(\mathrm{t})+\mathrm{V}_{\mathrm{d}}(\mathrm{t})\right]+\frac{\mathrm{R}_{\mathrm{d}} \mathrm{i}_{\mathrm{m}}^{2}}{2}+\frac{\mathrm{R}_{\mathrm{s}} \mathrm{i}_{\mathrm{m}}^{\beta+1}}{\pi} \int_{0}^{\pi} \sin ^{\beta+1}(\mathrm{t}) \mathrm{d}(\mathrm{t})$ (23)

Therefore, total conduction losses $P_{c}$ of MLI topology is obtained as equation (20) and (23)
$P_{C}=P_{C U}+P_{C B}$
The energy losses especially during on and off-states of the switches results in switching losses for a switching period of a switch. Hence there is a linear variation in voltage and current are related as follows [12][17]

$$
\begin{align*}
& P_{s w, o n}= \frac{1}{T} \int_{0}^{t_{o n}} V(t) \cdot i(t) d t \\
&= \frac{1}{T} \int_{0}^{t_{o n}}\left[\left(\frac{V_{s w}}{t_{o n}} t\right)\left(-\frac{I}{t_{o n}}\left(t-t_{o n}\right)\right)\right] d t \\
& \begin{aligned}
P_{s w, o n} & =\frac{1}{6 T}\left[V_{s w .} . \mathrm{I} . t_{o n}\right] \\
P_{s w, o f f} & =\frac{1}{T} \int_{0}^{t_{o f f}} V(t) . i(t) d t \\
& =\frac{1}{T} \int_{0}^{t_{o f f}}\left[\left(\frac{V_{s w}}{t_{o f f}} t\right)\left(-\frac{I}{t_{o f f}}\left(t-t_{o f f}\right)\right)\right] d t
\end{aligned}  \tag{25}\\
& \mathrm{P}_{\mathrm{sw}, o f f}=\frac{1}{6 \mathrm{~T}}\left[\mathrm{~V}_{\text {sw. }} . \mathrm{I} . \mathrm{t}_{\text {off }}\right]
\end{align*}
$$

Where T is a total time period and $P_{s w, o n}, P_{s w, o f f}$ are onstate, and off-state switching losses, $\mathrm{t}_{\mathrm{on}}, \mathrm{t}_{\text {off }}$ are the on, and off-state time periods respectively, and $V_{s w}$. is the peak voltage of the switch hence total switching losses $P_{s w}$ of multilevel inverter is expressed as
$\mathrm{P}_{\mathrm{SW}}=\mathrm{P}_{\mathrm{SW}, \text { on }}+\mathrm{P}_{\mathrm{SW}, \text { off }}$
Thus, the combination of conduction and switching losses gives the total power loss $\mathrm{P}_{\mathrm{L}}$; it can be expressed as $\mathrm{P}_{\mathrm{L}}=\mathrm{P}_{\mathrm{C}}+\mathrm{P}_{\mathrm{SW}}$

Further, the efficiency $\eta$ for the proposed inverter is
calculated as [39-40]
$\eta=\frac{\boldsymbol{P}_{\text {out }}}{\boldsymbol{P}_{\text {in }}}=\frac{\boldsymbol{P}_{\text {out }}}{\boldsymbol{P}_{\text {out }}+\boldsymbol{P}_{\boldsymbol{L}}}$
We can get the output power:

$$
\begin{equation*}
P_{o u t}=V_{r m s} * I_{r m s} \tag{30}
\end{equation*}
$$

Form Table VI, even though the number of power switches needed to produce five-level staircase outputs for designed topology is nominally high as considered with other topologies, the ambiguousness of the inverter, THD, power losses gets decreased. Considering that the components count per level factor $\boldsymbol{F}_{\boldsymbol{c c l}}$ value is more; then the topology requires more components to build the desired voltage level thus in the recent investigations, the primary aim is to decrease components count per level factor in the design of multilevel inverter. It is noticed that from Table V the proposed MLI is having fewer components count per level factor $\boldsymbol{F}_{\boldsymbol{c c l}}$ as related to other nine-level multilevel inverter topologies. Fig. 23 presents the comparison of the number of switches requires producing five-level output voltage steps. From Fig. 23, the introduced topology utilizes fewer
switches to correspondence topologies. Minimization of switches reduces the requirement of gate driver circuits for switches and limits components count per level factor $\boldsymbol{F}_{\boldsymbol{c c l}}$ hence reduce the complexity of the inverter. Fig. 23 represents the comparison result of the components count per
level factor $\boldsymbol{F}_{\boldsymbol{c c \boldsymbol { l }}}$ to develop a nine-levels of output. From Fig. 23, the proposed topology uses fewer components count per level factor $\boldsymbol{F}_{\boldsymbol{c c l}}$ in correlation with the different topologies.

Table V
The variance of variant 7 Level MLI topologies with regards number of output levels Nlev.

| Components required | CHB | NPC | FC | [35] | [38] | [20] | [38] | Proposed |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Number of switches (Ns) | $2\left(N_{\text {Lev }}{ }^{-1}\right)$ | $2\left(N_{\text {Lev }}-1\right)$ | $2\left(N_{\text {Lev }}-1\right)$ | $\left(\boldsymbol{N}_{\text {Lev }}+3\right)$ | $\left(\boldsymbol{N}_{L e v}+2\right)$ | $\left(N_{L e v}+1\right)$ | $\left(N_{L e v}{ }^{-1}\right)$ | $\frac{N_{\text {Lev }}+19}{4}$ |
| Number of diodes (Nd) | $2\left(N_{\text {Lev }}{ }^{-1}\right)$ | $2\left(N_{L e v}-1\right)$ | $2\left(N_{\text {Lev }}-1\right)$ | $\left(\boldsymbol{N}_{\text {Lev }}+3\right)$ | $\left(\boldsymbol{N}_{L e v}+2\right)$ | $\left(N_{L e v}+1\right)$ | $\left(N_{L e v}-1\right)$ | $\left(N_{L e v}{ }^{-1}\right)$ |
| Dc link capacitors (Ncap) | 0 | $\left(N_{L e v}-1\right)$ | $\left(N_{\text {Lev }}-1\right)$ | $\frac{N_{\text {Lev }}-1}{4}$ | $\frac{N_{L e v}-1}{4}$ | $\frac{N_{L e v}-1}{4}$ | $\frac{N_{\text {Lev }}-1}{4}$ | $\frac{N_{\text {Lev }}-1}{4}$ |
| Dc sources (n) | $\frac{N_{L e v}-1}{2}$ | $\frac{N_{\text {Lev }}-1}{8}$ | $\frac{N_{\text {Lev }}-1}{8}$ | $\frac{N_{\text {Lev }}-1}{8}$ | $\frac{N_{L e v}-1}{8}$ | $\frac{N_{\text {Lev }}-1}{8}$ | $\frac{N_{L e v}-1}{4}$ | $\frac{N_{\text {Lev }}-1}{4}$ |
| Number of driver board circuits (Ndk) | $2\left(N_{\text {Lev }}-1\right)$ | $2\left(N_{L e v}-1\right)$ | $2\left(N_{\text {Lev }}{ }^{-1}\right)$ | $\left(\boldsymbol{N}_{\text {Lev }}+3\right)$ | $\left(\boldsymbol{N}_{L e v}+2\right)$ | $\left(N_{L e v}+1\right)$ | $\left(N_{L e v}{ }^{-2}\right)$ | $\frac{N_{L e v}+19}{4}$ |

## A. COMPARISON STUDIES FOR 5 LEVEL MLI

Table VI
THE VARIANCE OF VARIANT 5 LEVEL MLI TOPOLOGIES WITH REGARDS NUMBER OF OUTPUT LEVELS

| Components required | CHB | $[35]$ | $[\mathbf{3 6}]$ | Proposed |
| :---: | :---: | :---: | :---: | :---: |
| Number of switches (Ns) | 8 | 8 | 8 | 5 |
| Number of diodes (Nd) | 8 | 8 | 8 | 5 |
| Dc link capacitors (Ncap) | 0 | 3 | 0 | 0 |
| Dc sources (n) | 2 | 1 | 2 | 3 |
| Number of other components (nx) | 0 | 2 | 0 | 0 |
| Number of driver board circuits (Ndk) | 8 | 8 | 8 | 5 |
| Components count per level (Fccl) | 5.2 | 6 | 5.2 | 3.6 |



FIGURE 23. (a) Comparison of components count per level of proposed MLI with other topologies.
(b) Comparison of Number of Switches to the proposed MLI with other topologies.

## B. COMPARISON STUDIES FOR 7 LEVEL MLI

Table VII
THE VARIANCE OF VARIANT 7 LEVEL MLI TOPOLOGIES WITH REGARDS NUMBER OF OUTPUT LEVELS

| Components required | CHB | NPC | FC | $[\mathbf{3 7 ]}$ | Proposed |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Number of switches (Ns) | 12 | 12 | 12 | 12 | 10 |
| Number of diodes (Nd) | 12 | 12 | 12 | 15 | 10 |
| Dc link capacitors (Ncap) | 3 | 6 | 6 | 6 | 0 |
| Dc sources (n) | 3 | 1 | 1 | 3 | 3 |
| Number of other components (nx) | 0 | 0 | 0 | 7 | 0 |


| Number of driver board circuits (Ndk) | 12 | 12 | 12 | 12 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Components count per level (Fccl) | 6 | 6.14 | 6.14 | 7.85 | 4.71 |



FIGURE 24. (a) Comparison of components count per level of proposed MLI with other topologies.
(b) Comparison of Number of Switches to the proposed MLI with other topologies

Form Table VII the number of power switches needed to produce seven-level staircase outputs for designed topology is less as considered with other topologies. Hence there is a reduction of gate driver circuits, so the ambiguousness of the inverter gets decreased. Considering that the components count per level factor $F_{c c l}$ value is more; then the topology requires more components to build the desired voltage level thus in the recent investigations, the primary objective is to decrease components count per level factor in the design of multilevel inverter. It is noticed that from Table III the proposed MLI is having fewer components count per level factor $F_{c c l}$ as related to other seven-level multilevel inverter topologies. Fig. 9 presents the comparison of the number of switches requires producing seven-level output voltage steps. From Fig. 9, the introduced topology utilizes fewer switches to correspondence topologies. Minimization of switches reduces the requirement of gate driver circuits for switches and limits components count per level factor $F_{c c l}$ hence reduce the complexity of the inverter. Fig. 27 represents the comparison result of the components count per level factor $F_{c c l}$ to develop a seven-level output. From Fig. 27, the proposed topology utilizes fewer components count per level factor $F_{c c l}$ in correlation with the different topologies.

## C. COMPARISON STUDIES FOR 15 LEVEL MLI

Form Table VIII the number of power switches needed to produce 15 -level staircase outputs for designed topology is less as considered with other topologies. Hence there is a reduction of gate driver circuits, so the ambiguousness of the inverter gets decreased. Considering that the components count per level factor $F_{c c l}$ value is more; then the topology requires more components to build the desired voltage level thus in the recent investigations, the primary objective is to decrease components count per level factor in the design of multilevel inverter. It is noticed that from Table VIII the proposed MLI is having fewer components count per level factor $F_{c c l}$ as related to other nine-level multilevel inverter topologies. Fig. 4 presents the comparison of the number of switches requires producing 15 -level output voltage steps. From Fig. 25, the introduced topology utilizes fewer switches to correspondence topologies. Minimization of switches reduces the requirement of gate driver circuits for switches and limits components count per level factor $\mathrm{F}_{\mathrm{ccl}}$ hence reduce the complexity of the inverter. Fig. 25 represents the comparison result of the components count per level factor $\mathrm{F}_{\mathrm{ccl}}$ to develop a 15-level output. From Fig. 25, the proposed topology utilizes fewer components count per level factor $\mathrm{F}_{\mathrm{ccl}}$ in correlated with the different topologies.

Table VIII
THE VARIANCE OF VARIANT 15 LEVEL MLI TOPOLOGIES WITH REGARDS NUMBER OF OUTPUT LEVELS

| Components required | FC | NPC | $[\mathbf{3 8}]$ | CHB | Proposed |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Number of switches (Ns) | 28 | 28 | 28 | 28 | 16 |
| Number of diodes (Nd) | 28 | 28 | 28 | 28 | 16 |
| Dc link capacitors (Ncap) | 14 | 14 | 0 | 7 | 0 |
| Dc sources (n) | 1 | 1 | 7 | 7 | 7 |
| Number of driver board circuits (Ndk) | 28 | 28 | 28 | 28 | 16 |
| Components count per level (Fccl) | 6.6 | 6.6 | 6.06 | 6.53 | 3.66 |



FIGURE 25. (a) Comparison of components count per level of proposed MLI with other topologies.
(b) Comparison of Number of Switches to the proposed MLI with other topologies

Therefore, the power losses and efficiency are calculated from equations 28 and 29. The total losses of five, seven and fifteen level MLI are $44.12 \mathrm{~W}, 49.05 \mathrm{~W}$ and 77.6 W respectively, which includes conduction losses of 44.072 W , 48.96 W and 77 W and switching losses of $0.054 \mathrm{~W}, 0.088 \mathrm{~W}$ and 0.315 W respectively. The efficiencies of five, seven and fifteen level MLI are calculated as $94.76 \%, 94.26 \%$ and $93.87 \%$ respectively and represented in Fig. 26.


## VII. CONCLUSION

The hybrid cascaded multilevel inverters with five, seven and fifteen levels with PEMFC powered systems are developed mathematically with simulation and experimental verification. A new control strategy, an adaptive neuro-fuzzy interference system (ANFIS) is implemented for the boost converter with which the output is accurate with the learning ability of the controller and is designed and realized. Efficiency and power loss for each multilevel inverter are calculated mathematically. The proposed topology gives good results in the reduction of power switching components, THD, driver circuits, stress on the devices and switching losses compared with the other topologies of multilevel inverters and generalized representation of these factors is illustrated. Simulation of boost converter for PEMFC input is presented to regulate the fuel flow input to
meet the desired output voltage with proper care on the transients occurring in the fuel stack. Single-phase multilevel inverters with hardware prototypes of five, seven, and fifteen levels and a boost converter with a fuel cell input are developed. The hardware results under dynamic loads are validated. To test the robustness of the proposed topology load disturbance test is conducted and observed that it is well stabilized for these conditions. Five, seven, and fifteen level MLI are compared with various existing topologies and provide many advantages in various factors in the design of MLI. The proposed topologies provide efficient results with a fuel cell stack.

## REFERENCES

[1] Lopez, Oscar, et al. "Multilevel multiphase space vector PWM algorithm with switching state redundancy." IEEE Transactions on industrial electronics 56.3 (2008): 792-804.
[2] Rodriguez, Jose, Jih-Sheng Lai, and Fang Zheng Peng. "Multilevel inverters: a survey of topologies, controls, and applications." IEEE Transactions on industrial electronics 49.4 (2002): 724-738.
[3] Rodríguez, José, et al. "Multilevel voltage-source-converter topologies for industrial medium-voltage drives." IEEE Transactions on industrial electronics 54.6 (2007): 2930-2945.
[4] Lai, Jih-Sheng, and Fang Zheng Peng. "Multilevel converters-a new breed of power converters." IEEE Transactions on industry applications 32.3 (1996): 509-517.
[5] Rodriguez, Jose, et al. "Multilevel converters: An enabling technology for high-power applications." Proceedings of the IEEE 97.11 (2009): 1786-1817.
[6] Wu, Jinn-Chang, et al. "Diode-clamped multilevel power converter with a zero-sequence current loop for three-phase threewire hybrid power filter." Electric Power Systems Research 81.2 (2011): 263-270.
[7] Wale, Sarala S., and Sunil K. Patil. "A developed single phase cascaded multilevel inverter with reduced number of power switches." 2017 Second International Conference on Electrical, Computer and Communication Technologies. IEEE, 2017.
[8] Rodriguez, Jose, et al. "A survey on neutral-point-clamped inverters." IEEE transactions on Industrial Electronics 57.7 (2009): 2219-2230.
[9] Carmo, Marcelo, et al. "A comprehensive review on PEM water electrolysis." International journal of hydrogen energy 38.12 (2013): 4901-4934.
[10]Guilbert, Damien, Stefania Maria Collura, and Angel Scipioni. "DC/DC converter topologies for electrolyzers: State-of-the-art and remaining key issues." International Journal of Hydrogen Energy 42.38 (2017): 23966-23985.
[11] Valdez-Resendiz, Jesus E., et al. "Continuous input-current buck-boost DC-DC converter for PEM fuel cell applications." International Journal of Hydrogen Energy 42.51 (2017): 30389-30399.
[12] Reddy, K. Jyotheeswara, and Sudhakar Natarajan. "Energy sources and multi-input DC-DC converters used in hybrid electric vehicle applications-A review." International Journal of Hydrogen Energy 43.36 (2018): 17387-17408.
[13]Gao, Dawei, et al. "Development and performance analysis of a hybrid fuel cell/battery bus with an axle integrated electric motor drive system." International Journal of Hydrogen Energy 41.2 (2016): 11611169.
[14]O'hayre, Ryan, et al. Fuel cell fundamentals. John Wiley \& Sons, 2016.
[15]Babaei, Ebrahim, Sara Laali, and Zahra Bayat. "A single-phase cascaded multilevel inverter based on a new basic unit with reduced number of power switches." IEEE Transactions on industrial electronics 62.2 (2014): 922-929.
[16]Babaei, Ebrahim, Somayeh Alilu, and Sara Laali. "A new general topology for cascaded multilevel inverters with reduced number of components based on developed H-bridge." IEEE Transactions on Industrial Electronics 61.8 (2013): 3932-3939.
[17]Babaei, Ebrahim, and Saeed Sheermohammadzadeh Gowgani. "Hybrid multilevel inverter using switched capacitor units." IEEE Transactions on Industrial Electronics 61.9 (2013): 4614-4621.
[18]Babaei, Ebrahim, and Seyed Hossein Hosseini. "New cascaded multilevel inverter topology with minimum number of switches." Energy Conversion and Management 50.11 (2009): 2761-2767.
[19]Babaei, Ebrahim, et al. "Reduction of dc voltage sources and switches in asymmetrical multilevel converters using a novel topology." Electric Power Systems Research 77.8 (2007): 1073-1085.
[20]Kangarlu, Mohammad Farhadi, and Ebrahim Babaei. "A generalized cascaded multilevel inverter using series connection of submultilevel inverters." IEEE transactions on power electronics 28.2 (2012): 625636.
[21]Saadi, Aïcha, et al. "Dynamic modeling and experimental analysis of PEMFCs: A comparative study." International Journal of Hydrogen Energy 42.2 (2017): 1544-1557.
[22]Harrag, Abdelghani, and Hamza Bahri. "Novel neural network ICbased variable step size fuel cell MPPT controller: performance, efficiency and lifetime improvement." International Journal of Hydrogen Energy 42.5 (2017): 3549-3563.
[23]Samosir, A. S., and A. H. M. Yatim. "Dynamic evolution control of bidirectional DC-DC converter for interfacing ultracapacitor energy storage to Fuel Cell Electric Vehicle system." 2008 Australasian Universities Power Engineering Conference. IEEE, 2008.
[24]Mekhilef, Saad, Rahman Saidur, and A. Safari. "Comparative study of different fuel cell technologies." Renewable and Sustainable Energy Reviews 16.1 (2012): 981-989.
[25]Sharaf, Omar Z., and Mehmet F. Orhan. "An overview of fuel cell technology: Fundamentals and applications." Renewable and sustainable energy reviews 32 (2014): 810-853.
[26]Rekioua, Djamila, Samia Bensmail, and Nabila Bettar. "Development of hybrid photovoltaic-fuel cell system for stand-alone application." International Journal of Hydrogen Energy 39.3 (2014): 1604-1611.
[27]Reddy, K. Jyotheeswara, and N. Sudhakar. "High voltage gain interleaved boost converter with neural network based MPPT controller for fuel cell based electric vehicle applications." IEEE Access 6 (2018): 3899-3908.
[28]Harrag, Abdelghani, and Sabir Messalti. "How fuzzy logic can improve PEM fuel cell MPPT performances?." International Journal of Hydrogen Energy 43.1 (2018): 537-550.
[29]Niu, Qun, Letian Zhang, and Kang Li. "A biogeography-based optimization algorithm with mutation strategies for model parameter estimation of solar and fuel cells." Energy conversion and management 86 (2014): 1173-1185.
[30]Becherif, M., and D. Hissel. "MPPT of a PEMFC based on air supply control of the motocompressor group." International Journal of Hydrogen Energy 35.22 (2010): 12521-12530.
[31]Benyahia, N., et al. "Power system simulation of fuel cell and supercapacitor based electric vehicle using an interleaving technique." International Journal of Hydrogen Energy 40.45 (2015): 15806-15814.
[32]Elmer, Theo, et al. "Fuel cell technology for domestic built environment applications: State of-the-art review." Renewable and Sustainable Energy Reviews 42 (2015): 913-931.
[33] Tania, H. M., Patra, J. K., John, V., Elangovan, D., \& Arunkumar, G. (2017). Four Level Boost Converter for Linear Loads. In Emerging Trends in Electrical, Communications and Information Technologies (pp. 369-376). Springer, Singapore.
[34]Reddy, K. Jyotheeswara, and N. Sudhakar. "ANFIS-MPPT control algorithm for a PEMFC system used in electric vehicle applications." International Journal of Hydrogen Energy 44.29 (2019): 15355-15369.
[35]Missula, Jagath Vallabhai, Ravindranath Adda, and Praveen Tripathya. "Pulse Width Modulation and SRF Based Closed-Loop Control of Stand-alone Single-phase 5L-ANPC Inverter." 2018 IEEE International Conference on Power Electronics, Drives and Energy Systems (PEDES). IEEE, 2018.
[36]Babaei, Ebrahim, and Seyed Hossein Hosseini. "New cascaded multilevel inverter topology with minimum number of switches." Energy Conversion and Management 50.11 (2009): 2761-2767.
[37]Birundha, S., and V. Saravanan. "Design and development of Z source cascaded seven level inverter for solar photovoltaic system." 2015 International Conference on Computation of Power, Energy, Information and Communication (ICCPEIC). IEEE, 2015.
[38]Beig, Abdul Rahiman, Udaya RY Kumar, and V. T. Ranganathan. "A novel fifteen level inverter for photovoltaic power supply system." Conference Record of the 2004 IEEE Industry Applications Conference, 2004. 39th IAS Annual Meeting. Vol. 2. IEEE, 2004
[39]Dhanamjayulu, C., Arunkumar, G., Jaganatha Pandian, B., \& Padmanaban, S. (2020). Design and implementation of a novel asymmetrical multilevel inverter optimal hardware components. International Transactions on Electrical Energy Systems, 30(2), e12201.
[40]C. Dhanamjayulu and S. Meikandasivam, "Implementation and Comparison of Symmetric and Asymmetric Multilevel Inverters for Dynamic Loads," in IEEE Access, vol. 6, pp. 738-746, 2018.


Dhanamjayulu C is a faculty and a member of the control and automation department in School of electrical engineering, Vellore Institute of Technology, Vellore, India. He has received the PhD degree in electronics engineering from Vellore Institute of Technology, Vellore, India, the M. Tech in control and instrumentation systems from Indian Institute of Technology, Madras, India and the B. Tech degree in electronics and communication engineering from JNTU University, Hyderabad, India. He is also an Assistant Professor Senior with the School of Electrical Engineering, Vellore Institute of Technology, Vellore, India. Since 2010, he has been an Assistant professor senior at Vellore Institute of Technology, Vellore, India. He was invited as a Visiting Researcher at the Department of Electrical Engineering, Aalborg University, Esbjerg, Denmark, funded by the Danida Mobility Grant, Ministry of Foreign Affairs of Denmark on Denmark's International Development Cooperation. He is perusing post doctorial fellowship in Aalborg University, Esbjerg, Denmark. His research activities are in the area of multilevel inverters, power converters, and active power filters and power quality.


Shaik Reddi Khasim received the B.Tech. Degree in electrical engineering with distinction from JNTUA, Andhra Pradesh, India, in 2012, the M. Tech. Degree with distinction from JNTUA, Andhra Pradesh, India, in 2015. He is perusing Ph.D. degree in the field of Power Electronics at Vellore Institute of Technology, Vellore, India. His research activities are in the area of multilevel inverters, power converters and electric vehicles.


Sanjeevikumar Padmanaban (M'12-SM'15, IEEE) received the bachelor's degree in electrical engineering from the University of Madras, Chennai, India, in 2002, the master's degree (Hons.) in electrical engineering from Pondicherry University, Puducherry, India, in 2006, and the PhD degree in electrical engineering from the University of Bologna, Bologna, Italy, in 2012. He was an Associate Professor with VIT University from 2012 to 2013. In 2013, he joined the National Institute of Technology, India, as a Faculty Member. In 2014, he was invited as a Visiting Researcher at the Department of Electrical Engineering, Qatar University, Doha, Qatar, funded by the Qatar National Research Foundation (Government of Qatar). He continued his research activities with the Dublin Institute of Technology, Dublin, Ireland, in 2014. Further, he served an Associate Professor with the Department of Electrical and Electronics Engineering, University of Johannesburg, Johannesburg, South Africa, from 2016 to 2018. Since 2018, he has been a Faculty Member with the Department of Energy Technology, Aalborg University, Esbjerg, Denmark. He has authored more than 300 scientific papers. S. Padmanaban was the recipient of the Best Paper cum Most Excellence Research Paper Award from IET-SEISCON'13, IET-CEAT'16, IEEEEECSI'19, IEEE-CENCON'19 and five best paper awards from ETAEERE'16 sponsored Lecture Notes in Electrical Engineering, Springer book. He is a Fellow of the Institution of Engineers, India, the Institution of Electronics and Telecommunication Engineers, India, and the Institution of Engineering and Technology, U.K. He is an Editor/Associate Editor/Editorial Board for refereed journals, in particular the IEEE SYSTEMS JOURNAL, IEEE Transaction on Industry Applications, IEEE ACCESS, IET Power Electronics, IET Electronics Letters, and Wiley-International Transactions on Electrical Energy Systems, Subject Editorial Board Member - Energy Sources - Energies Journal, MDPI, and the Subject Editor for the IET Renewable Power Generation, IET Generation, Transmission and Distribution, and FACTS journal (Canada).


Arunkumar G has received a Bachelor Degree in Electrical and Electronics Engineering in 2002 and Master Degree (Power Electronics) in 2005. He completed his PhD. Degree at Anna university, Tamilnadu, India in 2015. Since 2015, he is working as an Associate Professor in the School of Electrical Engineering, VIT University, Vellore.


JENS BO HOLM-NIELSEN, Born 1954; PhD.
JENS BO HOLM-NIELSEN, Born 1954; PhD.
Head of the Research Group of Bioenergy and Green Engineering, Department of Energy Green Engineering, Department of Energy
Technology, Aalborg University, Denmark. 30 years of experience in the field of Biomass feedstock production, Biorefinery concepts and
Biogas production. Board member of $R \& D$, feedstock production, Biorefinery concepts and
Biogas production. Board member of $R \& D$, committees of the cross-governmental body of biogas developments 1993-2009, Denmark. biogas developments 1993-2009, Denmark.
Secretary and/or chair of NGO biogas and bioenergy organizations. Chair and presenter of Sustainable and 100 per cent Renewables and SDG-17 goals. Experience of a variety of EU projects, organizer of international conferences, workshops and training programs in EU, USA, Canada, China, Brazil, India, Iran, Russia, Ukraine, among others. Research: Managing research, development and demonstration programs in Integrated agriculture, environment and energy systems. Fulfilled the biomass and bio-energy R \& D projects. His principle focuses on biofuels, biogas and biomass resources. EDU and Supervising M.Sc. and PhD students in these research fields. Training programs: International courses, training programs, and supervision for PhD students and academic staff, governmental bodies and experts in bioenergy systems. His full biography at www.aau.dk-profile search Jens Bo Holm-Nielsen


FREDE BLAABJERG (S'86-M'88-SM'97F'03) was with ABB-Scandia, Randers, Denmark, from 1987 to 1988. From 1988 to 1992, he got the PhD degree in Electrical Engineering at Aalborg University in 1995. He became an Assistant Professor in 1992, an Associate Professor in 1996, and a Full Professor of power electronics and drives in 1998. From 2017 he became a Villum Investigator. He is honoris causa at University Politehnica Timisoara (UPT), Romania and Tallinn Technical University (TTU) in Estonia.
His current research interests include power electronics and its applications such as in wind turbines, PV systems, reliability, harmonics and adjustable speed drives. He has published more than 600 journal papers in the fields of power electronics and its applications. He is the co-author of four monographs and editor of ten books in power electronics and its applications.

He has received 32 IEEE Prize Paper Awards, the IEEE PELS Distinguished Service Award in 2009, the EPE-PEMC Council Award in 2010, the IEEE William E. Newell Power Electronics Award 2014, the Villum Kann Rasmussen Research Award 2014, the Global Energy Prize in 2019, and the 2020 IEEE Edison Medal. He was the Editor-in-Chief of the IEEE Transactions on Power Electronics from 2006 to 2012. He has been Distinguished Lecturer for the IEEE Power Electronics Society from 2005 to 2007 and for the IEEE Industry Applications Society from 2010 to 2011 as well as 2017 to 2018. In 2019-2020 he serves a President of IEEE Power Electronics Society. He is Vice-President of the Danish Academy of Technical Sciences too. He is nominated in 2014-2019 by Thomson Reuters to be between the most 250 cited researchers in Engineering in the world. In 2017 he became Honoris Causa at University Politehnica Timisoara (UPT), Romania.

